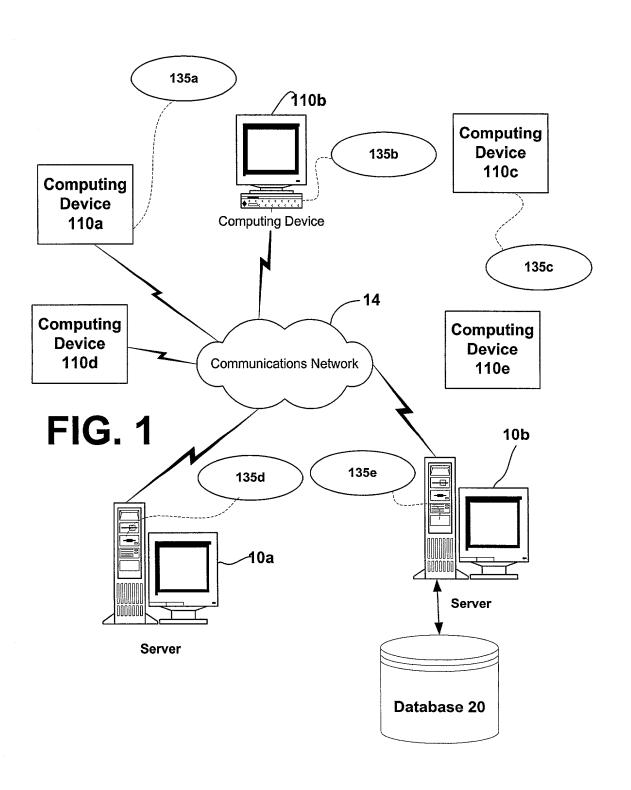
Docket No.: MSFT-0579/167505.2 Inventors: Christopher B. Weare Filing Date: August 20, 2001 Serial No.: Not yet assigned Title: System and Methods for Providing Adaptive

Property Classification

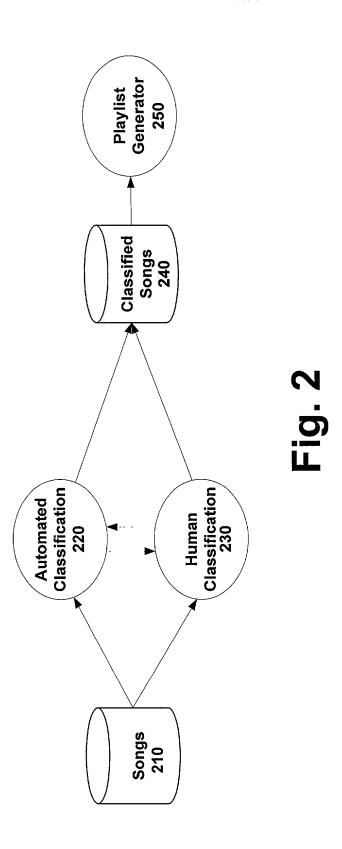
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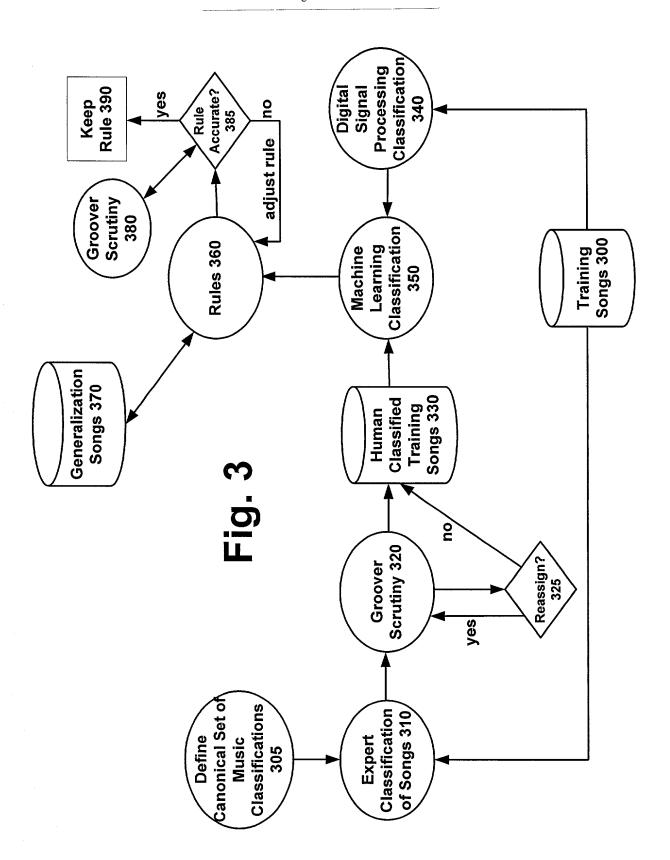
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Fig. 4A

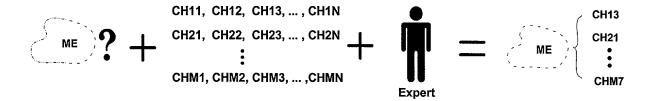


Fig. 4B

Fig. 4C

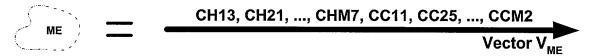
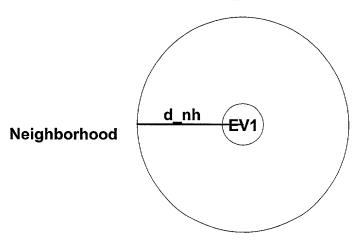


Fig. 4D



The state of the s

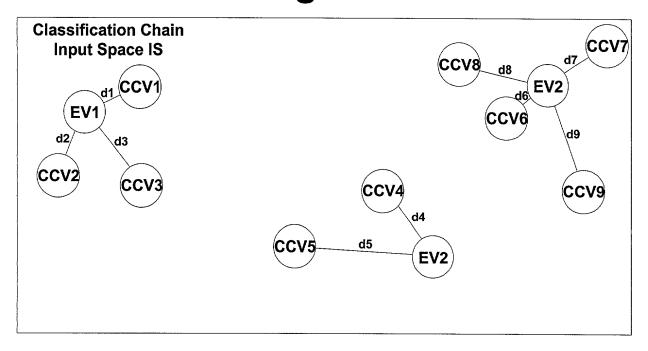
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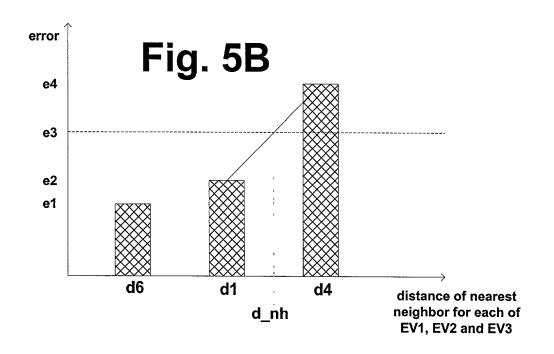
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Fig. 5A





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Fig. 6A

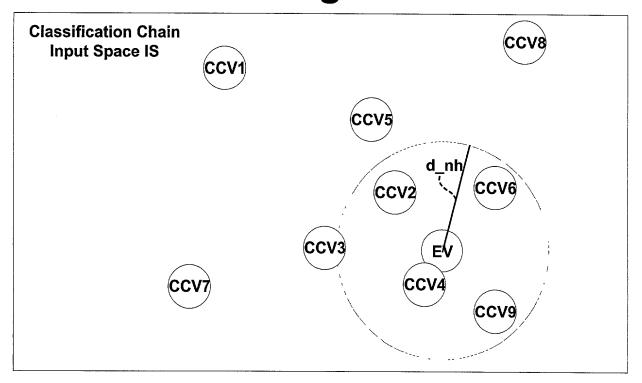
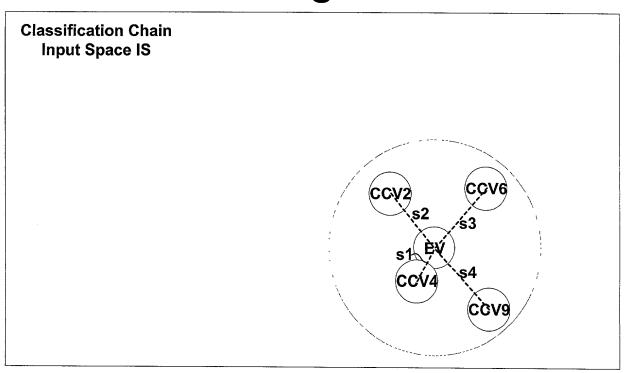


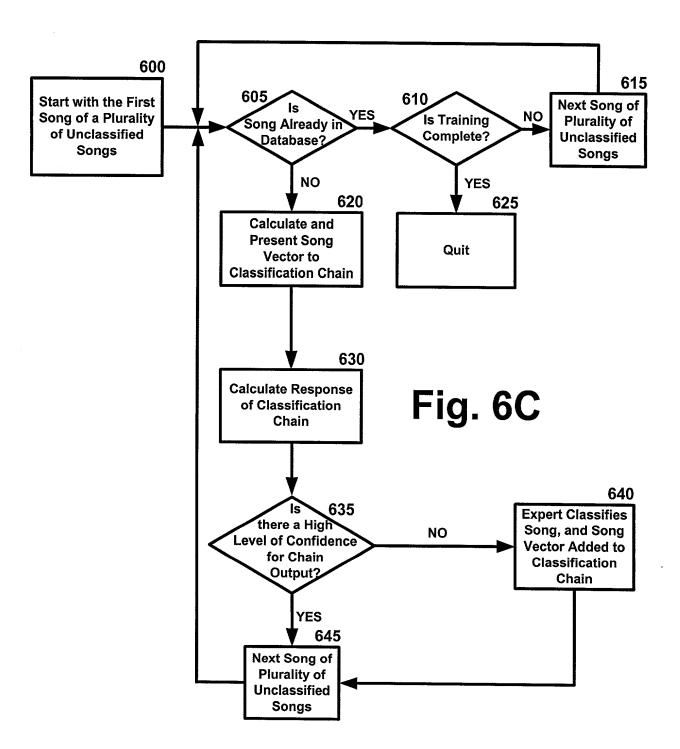
Fig. 6B



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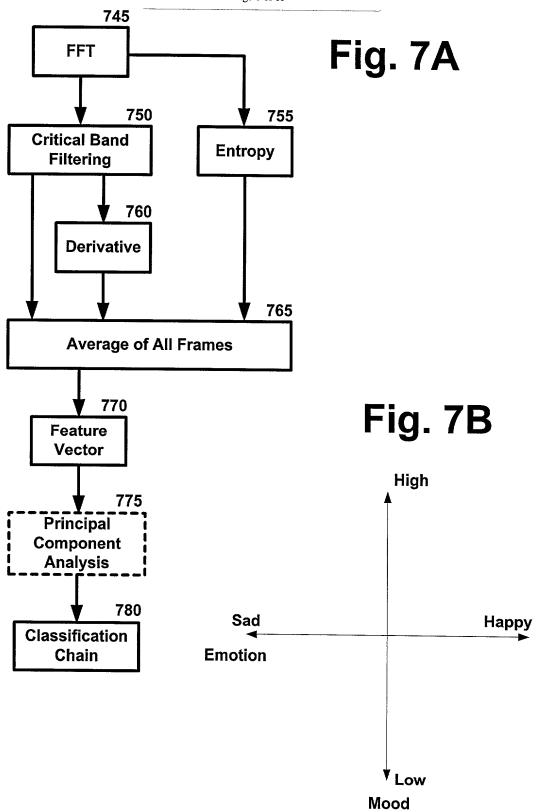
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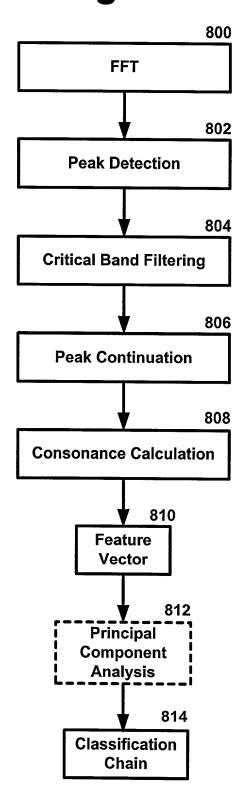


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Fig. 8A



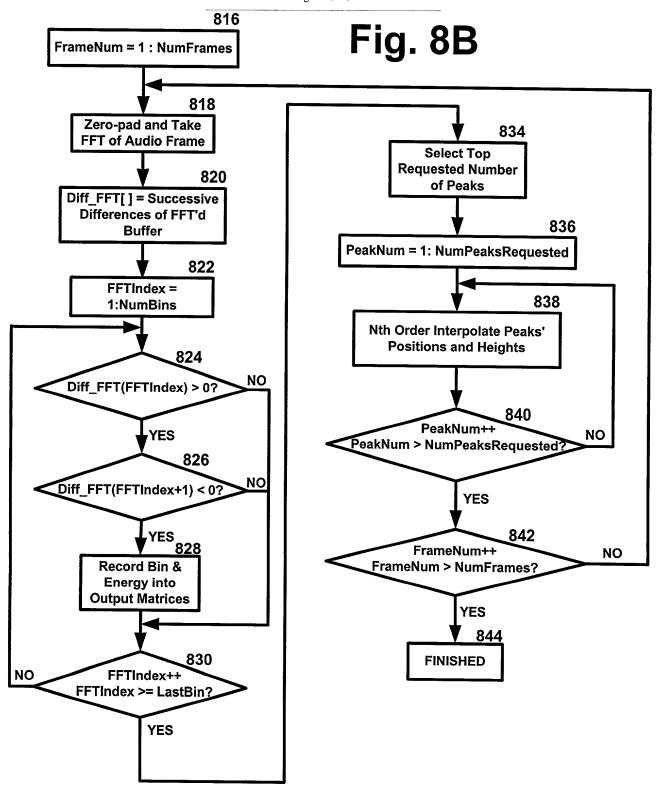
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in First Frame

PeakMatched = []

GuideMatch = 0

MinDiff = kNyquistFreq Matched = 0

If ((ThisPeak

not Just Continued))

GuideMatch = GuideNum

(Record Matched Guide #)

guideNum++

(guideNum>numGuides)?

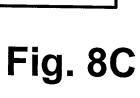
YES

NO

YES

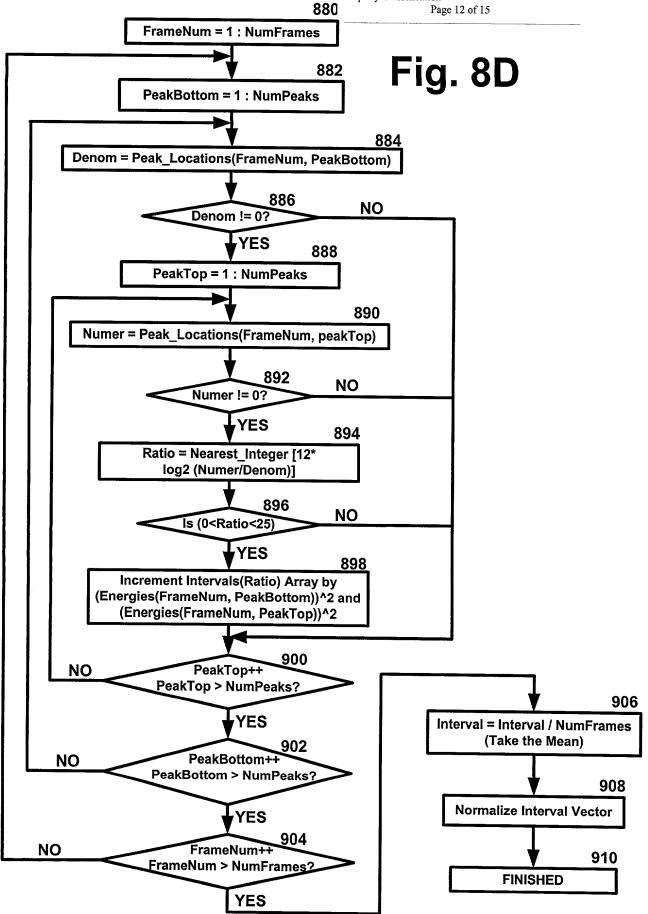
850

Docket No.: MSFT-0579/167505.2 Inventors: Christopher B. Weare Filing Date: August 20, 2001 Serial No.: Not yet assigned Title: System and Methods for Providing Adaptive Property Classification 846 Page 11 of 15 Setup Guides Based on Peaks 866 NO GuideMatch != 0 848 YES For FrameNum = 1: NumFrames 868 Record this Peak & Energy into Output Matrix Record Possible Missed Peak in Previous Frame if ThisGuide Just Started PeakMatched(PeakNum) = 1 GuideState(GuideNum) = kContinued 852 GuideEnergy(GuideNum) = ThisEnergy For PeakNum = 1:NumPeaks 870 PeakNum++ 854 PeakNum > NumPeaks? YES ThisPeak = Bins(FrameNum, PeakNum) 872 ThisEnergy = Energies(FrameNum, PeakNum) **Locate & Record Unused Guides** and Unmatched Peaks 856 For GuideNum = 1:NumGuides 874 NO Any Unused Guides 858 or Unmatched Peaks? ThisGuide = GuideFreq(GuideNum) ThisGuideEnergy = GuideEnergy(GuideNum) **YES** 876 Start New Guides at the Unmatched Peaks with Largest 860 **Energy** Is within 1/2 Step of ThisGuide) NO & (PeakEnergy is within 6dB of ThisGuideEnergy) & (ThisGuide 878 FrameNum++ NO FrameNum > NumFrames? 862 YES 879 **FINISHED** 864



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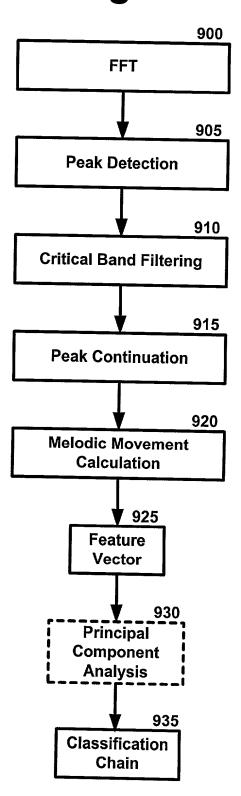


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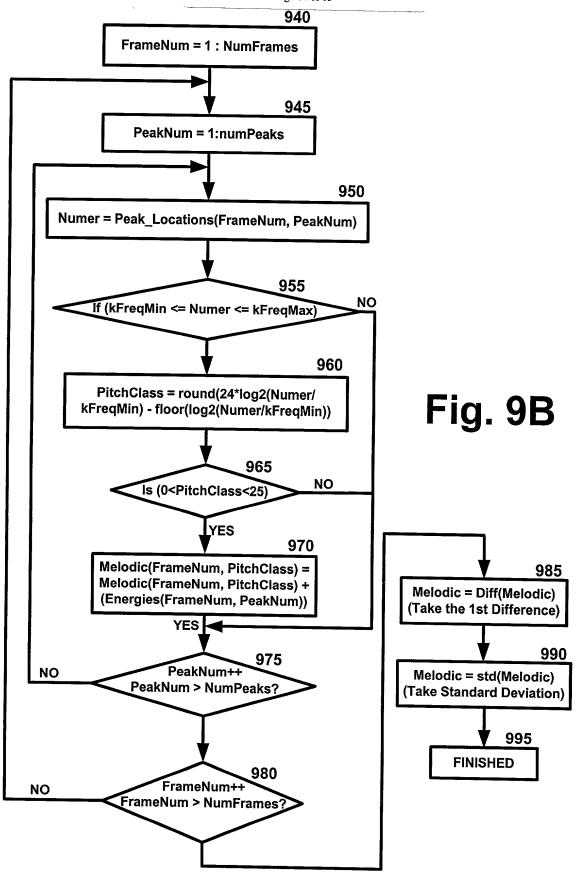
Fig. 9A



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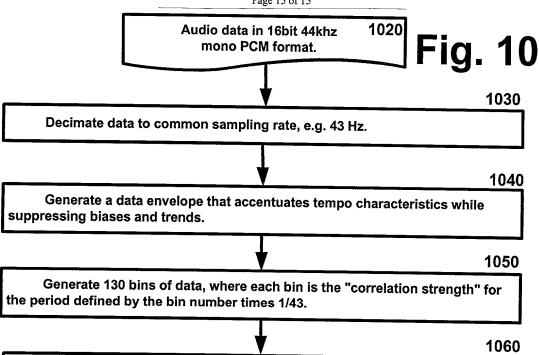
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Feed into classification chain. For every calculated distance that is below a defined threshold, the corresponding classified tempo along with the distance is added to a table. The distance values in the table are translated into confidence values by taking 1/(distance^4). Each tempo value is divided by 10 and the log2 is taken. The integer portion is the "harmonic component" entry. The fractional portion is the "tempo component" entry.

1070

Tempo components are translated into vector representation. The range of 0 to 1 is mapped to 0 to 2pi. The sine and cosine of the angle are taken and multiplied by the corresponding confidence value. These sine and cosine components for the entire table are accumulated separately to create an overall representative vector. The angle of this vector is mapped back to a range of 0 to 1 to give an overall confidence of the tempo classification.

1080

The harmonic component of each table entry is evaluated. If the corresponding tempo component meets one of the following criteria, the harmonic is modified. If the tempo entry is less than the overall tempo classification - 0.5, the harmonic component entry is decremented. If the tempo entry is greater than the overall tempo classification + 0.5, the harmonic component is incremented. Each harmonic component table entry "votes" for its value with a weight proportional to the corresponding confidence value. The most prominent value is used as the overall harmonic component.

1090

The overall tempo is calculated by calculating 2^(overall harmonic component + overall tempo component) multiplied by 10.